

Test 1

This test is graded out of 47 marks. No books, notes, graphing calculators or cell phones are allowed. You must show all your work, the correct answer is worth 1 mark the remaining marks are given for the work. If you need more space for your answer use the back of the page.

Question 1.

a. (6 marks) Solve the following system by Gauss-Jordan elimination:

$$\begin{aligned} 3x_1 - 2x_2 + x_3 - 3x_4 + x_5 &= 0 \\ 4x_1 + 3x_2 - x_3 + x_4 - 2x_5 &= 0 \\ 7x_1 + x_2 - 2x_4 - x_5 &= 0 \\ x_3 - x_4 &= 0 \end{aligned}$$

b. (2 marks) Find two particular nontrivial solution to the above system.

$$\begin{bmatrix} 3 & -2 & 1 & -3 & 1 & 0 \\ 4 & 3 & -1 & 1 & -2 & 0 \\ 7 & 1 & 0 & -2 & -1 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{l} \sim 3R_2 \rightarrow R_2 \\ 3R_3 \rightarrow R_3 \end{array} \begin{bmatrix} 3 & -2 & 1 & -3 & 1 & 0 \\ 12 & 9 & -3 & 3 & -6 & 0 \\ 21 & 3 & 0 & -6 & -3 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{l} \sim -4R_1 + R_2 \\ -7R_1 + R_3 \end{array} \begin{bmatrix} 3 & -2 & 1 & -3 & 1 & 0 \\ 0 & 17 & -7 & 15 & -10 & 0 \\ 0 & 17 & -7 & 15 & -10 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \end{bmatrix}$$

$$\sim -R_2 + R_3 \rightarrow R_3 \begin{bmatrix} 3 & -2 & 1 & -3 & 1 & 0 \\ 0 & 17 & -7 & 15 & -10 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \end{bmatrix}$$

$$\sim R_3 \leftrightarrow R_4 \begin{bmatrix} 3 & -2 & 1 & -3 & 1 & 0 \\ 0 & 17 & -7 & 15 & -10 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{l} \sim -R_3 + R_1 \rightarrow R_1 \\ 7R_3 + R_2 \rightarrow R_2 \end{array} \begin{bmatrix} 3 & -2 & 0 & -2 & 1 & 0 \\ 0 & 17 & 0 & 8 & -10 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$17R_1 \rightarrow R_1 \begin{bmatrix} 51 & -34 & 0 & -34 & 17 & 0 \\ 0 & 17 & 0 & 8 & -10 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\sim 2R_2 + R_1 \rightarrow R_1 \begin{bmatrix} 51 & 0 & 0 & -18 & -3 & 0 \\ 0 & 17 & 0 & 8 & -10 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{l} \sim \frac{1}{51}R_1 \rightarrow R_1 \\ \frac{1}{17}R_2 \rightarrow R_2 \end{array} \begin{bmatrix} 1 & 0 & 0 & -\frac{18}{51} & -\frac{3}{51} & 0 \\ 0 & 1 & 0 & \frac{8}{17} & -\frac{10}{17} & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

x_4 & x_5 are free var.

$$\begin{aligned} x_4 &= s \\ x_5 &= t \end{aligned} \quad s, t \in \mathbb{R}$$

$$\begin{aligned} \therefore x &= (x_1, x_2, x_3, x_4, x_5) \\ &= \left(\frac{6}{17}s + \frac{1}{17}t, -\frac{8}{17}s + \frac{10}{17}t, s, s, t \right) \end{aligned}$$

$$\begin{aligned} \text{b) } s=0, t=1 \quad x &= \left(\frac{1}{17}, \frac{10}{17}, 0, 0, 1 \right) \\ s=1, t=0 \quad x &= \left(\frac{6}{17}, -\frac{8}{17}, 1, 1, 0 \right) \end{aligned}$$

Question 2. Consider the matrices:

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}, B = \begin{bmatrix} 2 & 2 & 1 \\ 0 & -4 & 0 \end{bmatrix}, C = \begin{bmatrix} 0 & 1 \\ -3 & 0 \\ 3 & -1 \end{bmatrix}, D = \begin{bmatrix} 0 & 1 \\ 1 & -2 \end{bmatrix}, F = \begin{bmatrix} 1 & -1 \\ 0 & -2 \\ 1 & -3 \end{bmatrix}$$

a. (2 marks) Compute the following, if possible.

$$\text{tr}(BC)$$

$$\text{tr} \left(\begin{bmatrix} 2 & 2 & 1 \\ 0 & -4 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -3 & 0 \\ 3 & -1 \end{bmatrix} \right) = \text{tr} \left(\begin{bmatrix} -3 & 1 \\ 12 & 0 \end{bmatrix} \right)$$

b. (2 marks) Compute the following, if possible.

$$A^{-2}$$

A is invertible since the elements of the main diagonal are non zero. So

c. (6 marks) Find E, if possible.

$$\begin{aligned} (\text{tr}(D)D - E^t)^{-1} &= BA^{-2}F \\ \left[(\text{tr}(D)D - E^t)^{-1} \right]^{-1} &= [BA^{-2}F]^{-1} A^{-2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1/4 \end{bmatrix} \\ \text{tr}(D)D - E^t &= [BA^{-2}F]^{-1} \end{aligned}$$

$$\begin{aligned} E^t &= \text{tr}(D)D - [BA^{-2}F]^{-1} \\ E &= (\text{tr}(D)D - [BA^{-2}F]^{-1})^t \end{aligned}$$

So $\text{tr}(D) = -2$

$$BA^{-2}F = \begin{bmatrix} 2 & 2 & 1 \\ 0 & -4 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1/4 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & -2 \\ 1 & -3 \end{bmatrix} = \begin{bmatrix} 2 & 2 & 1 \\ 0 & -4 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & -2 \\ 1/4 & -3/4 \end{bmatrix} = \begin{bmatrix} 9/4 & -27/4 \\ 0 & 8 \end{bmatrix}$$

$$[BA^{-2}F]^{-1} = \frac{1}{18} \begin{bmatrix} 8 & 27/4 \\ 0 & 9/4 \end{bmatrix} = \begin{bmatrix} 4/9 & 3/8 \\ 0 & 1/8 \end{bmatrix}$$

$$E = \left(-2 \begin{bmatrix} 0 & 1 \\ 1 & -2 \end{bmatrix} - \begin{bmatrix} 4/9 & 3/8 \\ 0 & 1/8 \end{bmatrix} \right)^t$$

$$= \begin{bmatrix} -4/9 & -19/8 \\ -2 & 3/8 \end{bmatrix}^t$$

$$= \begin{bmatrix} -4/9 & -2 \\ -19/8 & 3/8 \end{bmatrix}$$

Question 3. Consider

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 3 \end{bmatrix}$$

- a. (4 marks) Find A^{-1} .
 b. (2 marks) Write A^{-1} as a product of elementary matrices.
 c. (2 marks) Using a. solve $Ax = b$ where $x = [x_1, x_2, x_3]^t$ and $b = [1, -2, 1]^t$.

a) $[A \mid I]$

$$= \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & 3 & 0 & 0 & 1 \end{array} \right]$$

$$\sim \begin{array}{c} \frac{1}{3}R_3 \rightarrow R_3 \end{array} \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & \frac{1}{3} \end{array} \right]$$

$$\sim \begin{array}{c} -3R_3 + R_1 \rightarrow R_1 \\ -2R_3 + R_2 \rightarrow R_2 \end{array} \left[\begin{array}{ccc|ccc} 1 & 2 & 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & 1 & -\frac{2}{3} \\ 0 & 0 & 1 & 0 & 0 & \frac{1}{3} \end{array} \right]$$

$$\sim \begin{array}{c} -2R_2 + R_1 \rightarrow R_1 \end{array} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -2 & \frac{1}{3} \\ 0 & 1 & 0 & 0 & 1 & -\frac{2}{3} \\ 0 & 0 & 1 & 0 & 0 & \frac{1}{3} \end{array} \right]$$

$\therefore A$ is invertible $A^{-1} = \begin{bmatrix} 1 & -2 & \frac{1}{3} \\ 0 & 1 & -\frac{2}{3} \\ 0 & 0 & \frac{1}{3} \end{bmatrix}$

b) $E_4 E_3 E_2 E_1 A = I$

So $A^{-1} = E_4 E_3 E_2 E_1$

where

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix}, \quad E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_2 = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad E_4 = \begin{bmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

c) $Ax = b$

$$A^{-1}Ax = A^{-1}b$$

$$Ix = A^{-1}b$$

$$x = A^{-1}b$$

$$= \begin{bmatrix} 1 & -2 & \frac{1}{3} \\ 0 & 1 & -\frac{2}{3} \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{16}{3} \\ -\frac{8}{3} \\ \frac{1}{3} \end{bmatrix}$$

Question 4.¹

a. (2 marks) Let $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$. Find a 2×2 matrix B such that $AB = 0$ but $BA \neq 0$.

b. Let A and B be non-zero $n \times n$ matrices such that $AB = 0$ but $BA \neq 0$.

i. (2 marks) Prove that $(BA)^2 = 0$

ii. (2 marks) Prove that B is singular.

$$a) \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} = 0$$

$$b_{11} + b_{21} = 0 \quad b_{11} = -b_{21}$$

$$b_{12} + b_{22} = 0 \quad b_{12} = -b_{22}$$

$$\begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \neq 0$$

$$b_{11} + b_{12} \neq 0$$

$$\text{or } b_{21} + b_{22} \neq 0$$

$$\text{So let } b_{11} = 1$$

$$b_{22} = 2$$

$$B = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} \checkmark$$

$$bii) (BA)^2 = BABA$$

$$= BOA \text{ from premise } AB=0$$

$$= 0$$

ii) Suppose that B is invertible.

$$BB^{-1} = I$$

$$ABB^{-1} = AI$$

$$0B^{-1} = A$$

$$0 = A \quad \checkmark \text{ A is nonzero}$$

$\therefore B$ is not invertible

$\therefore B$ is singular.

Question 5.² (4 marks) Let

$$A = \begin{bmatrix} 2 & 1 \\ x & y \end{bmatrix}$$

Find x and y such that A^2 is symmetric, if possible.

$$A^2 = AA$$

$$= \begin{bmatrix} 2 & 1 \\ x & y \end{bmatrix} \begin{bmatrix} 2 & 1 \\ x & y \end{bmatrix}$$

$$= \begin{bmatrix} 4+x & 2+y \\ 2x+xy & x+y^2 \end{bmatrix}$$

$$(A^2)^T = A^2$$

$$\begin{bmatrix} 4+x & 2x+xy \\ 2+y & x+y^2 \end{bmatrix} = \begin{bmatrix} 4+x & 2+y \\ 2x+xy & x+y^2 \end{bmatrix}$$

$$\text{So } 2+y = 2x+xy$$

$$0 = 2x+xy - 2 - y$$

$$0 = x(2+y) - (2+y)$$

$$0 = (x-1)(2+y)$$

$$x=1 \quad y=-2$$

So if $x=1$ then $y \in \mathbb{R}$
and if $y=-2$ then $x \in \mathbb{R}$

¹From a John Abbott Final Examination

²From a John Abbott Final Examination

Question 6.³ A matrix X is called a *weak generalized inverse* of A if $AXA = A$

a. (3 marks) For what value of k is $\begin{bmatrix} k & k \\ k & k \\ k & k \end{bmatrix}$ a weak generalized inverse of $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$.

b. (2 marks) Show that if the system $Ax = b$ is consistent then Xb will be a solution to this system

$$\begin{aligned}
 AXA &= \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} k & k \\ k & k \\ k & k \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} k+k & k+k & k+k \\ k+k & k+k & k+k \\ k+k & k+k & k+k \end{bmatrix} \\
 &= \begin{bmatrix} (k+k)+(k+k)+(k+k) & (k+k)+(k+k)+(k+k) \\ (k+k)+(k+k)+(k+k) & (k+k)+(k+k)+(k+k) \end{bmatrix} \\
 &= \begin{bmatrix} 6k & 6k & 6k \\ 6k & 6k & 6k \end{bmatrix}
 \end{aligned}$$

So $AXA = A$
if $k = 1/6$

b) AXb
 $= AXAx_1$
 $= Ax_1$
 $= b$

Since $Ax = b$ is consistent
 $\exists x_1$ s.t. $Ax_1 = b$

since $A = AXA$

$\therefore Xb$ is a solution to $Ax = b$.

Question 7. (6 marks) Consider the following system:

$$\begin{aligned} x + y + 7z &= c_1 \\ x + 2y + 3z &= c_2 \\ 2x + 3y + 10z &= 1 \end{aligned}$$

and

$$\begin{aligned} 2x + y - 7z &= c_1 \\ 3x - 2y + 3z &= c_2 \\ 7x &= 0 \end{aligned}$$

. If any, for what value(s) of c_1, c_2 are both system consistent.

$$\begin{bmatrix} 1 & 1 & 7 & c_1 \\ 1 & 2 & 3 & c_2 \\ 2 & 3 & 10 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & -7 & c_1 \\ 3 & -2 & 3 & c_2 \\ 7 & 0 & -11 & 0 \end{bmatrix}$$

$$\sim \begin{array}{l} -R_3 + R_2 \rightarrow R_2 \\ -2R_1 + R_3 \rightarrow R_3 \end{array} \begin{bmatrix} 1 & 1 & 7 & c_1 \\ 0 & 1 & -4 & c_2 - c_1 \\ 0 & 1 & -4 & 1 - 2c_1 \end{bmatrix}$$

$$\sim \begin{array}{l} 2R_2 \rightarrow R_2 \\ 2R_3 \rightarrow R_3 \end{array} \begin{bmatrix} 2 & 1 & -7 & c_1 \\ 6 & -4 & 6 & 2c_2 \\ 14 & 0 & -22 & 0 \end{bmatrix}$$

$$\sim \begin{array}{l} -R_2 + R_3 \rightarrow R_3 \end{array} \begin{bmatrix} 1 & 1 & 7 & c_1 \\ 0 & 1 & -4 & c_2 - c_1 \\ 0 & 0 & 0 & -c_2 - c_1 + 1 \end{bmatrix}$$

$$\sim \begin{array}{l} -3R_1 + R_2 \rightarrow R_2 \\ -7R_1 + R_3 \rightarrow R_3 \end{array} \begin{bmatrix} 2 & 1 & -7 & c_1 \\ 0 & -7 & 27 & 2c_2 - 3c_1 \\ 0 & -7 & 27 & -7c_1 \end{bmatrix}$$

this system is consistent

$$\text{if } -c_2 - c_1 + 1 = 0$$

$$c_1 + c_2 = 1$$

$$c_1 = -c_2 + 1$$

$$\sim \begin{array}{l} -R_2 + R_3 \rightarrow R_3 \end{array} \begin{bmatrix} 2 & 1 & -7 & c_1 \\ 0 & -7 & 27 & 2c_2 - 3c_1 \\ 0 & 0 & 0 & -4c_1 - 2c_2 \end{bmatrix}$$

this system is consistent

$$\text{if } -4c_1 - 2c_2 = 0$$

$$4c_1 + 2c_2 = 0$$

\therefore both system are consistent if

$$4(-c_2 + 1) + 2c_2 = 0$$

$$-4c_2 + 4 + 2c_2 = 0$$

$$4 = 2c_2$$

$$c_2 = 2$$

and

$$c_1 = -2 + 1 = -1$$

Bonus Question. (5 marks) If A is 2×2 , show that $A^{-1} = A^T$ if and only if $A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$ for some θ or $A = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$.

[\Leftarrow]

Let $A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$ then $A^{-1} = \frac{1}{\cos^2 \theta + \sin^2 \theta} \begin{bmatrix} \cos \theta & -\sin \theta \\ +\sin \theta & \cos \theta \end{bmatrix}$

$$= \frac{1}{1} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$\therefore A^{-1} = A^T$

Let $A = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$ then $A^{-1} = \frac{1}{-\cos^2 \theta - \sin^2 \theta} \begin{bmatrix} -\cos \theta & -\sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$

$= - \begin{bmatrix} -\cos \theta & -\sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$

$= \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$

[\Rightarrow]

$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, A^T = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$

$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

$A^{-1} = A^T$

$\frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$

Let $k = ad - bc$

$\begin{bmatrix} d/k & -b/k \\ -c/k & a/k \end{bmatrix} = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$

① $\frac{d}{k} = a \Leftrightarrow d = ak$ ③

④ $\frac{a}{k} = d \Leftrightarrow a = dk$ ②

By ①, ②, ③, ④ it follows that

$k = \pm 1$

if $k = 1$ then $d = a$ and $-b = c$

So we have

$1 = ad - bc$

$1 = a^2 + b^2$

Let $a = \cos \theta$
 $b = \sin \theta$

for some θ .

and we get

$A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$

if $k = -1$

we get

$A = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$.