

Books, watches, notes or cell phones are not allowed. The only calculators allowed are the Sharp EL-531\*\*. You must show all your work, the correct answer is worth 1 mark the remaining marks are given for the work.

**Question 1.** (5 marks) Prove that if  $\{\vec{v}_1, \vec{v}_2\}$  is linearly independent and  $\vec{v}_3$  does not lie in  $\text{span}\{\vec{v}_1, \vec{v}_2\}$ , then  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is linearly independent.

Suppose  $\{\underline{v}_1, \underline{v}_2, \underline{v}_3\}$  is linearly dependent then  $\exists c_i \neq 0$  s.t.  $c_1 \underline{v}_1 + c_2 \underline{v}_2 + c_3 \underline{v}_3 = \underline{0}$

Case:  $c_3 = 0 \Rightarrow c_1 \neq 0$  or  $c_2 \neq 0$

$$\underline{0} = c_1 \underline{v}_1 + c_2 \underline{v}_2 + c_3 \underline{v}_3$$

$$\underline{0} = c_1 \underline{v}_1 + c_2 \underline{v}_2 + 0 \underline{v}_3$$

$\underline{0} = c_1 \underline{v}_1 + c_2 \underline{v}_2 \Rightarrow \{\underline{v}_1, \underline{v}_2\}$  is lin. dep  $\downarrow$   
 since  $\{\underline{v}_1, \underline{v}_2\}$  is lin. ind.  
 by promise.

Case:  $c_3 \neq 0 \Rightarrow \underline{0} = c_1 \underline{v}_1 + c_2 \underline{v}_2 + c_3 \underline{v}_3$

$$\underline{v}_3 = -\frac{c_1}{c_3} \underline{v}_1 - \frac{c_2}{c_3} \underline{v}_2$$

$\Rightarrow \underline{v}_3 \in \text{span}\{\underline{v}_1, \underline{v}_2\} \downarrow$  since  
 $\underline{v}_3 \notin \text{span}\{\underline{v}_1, \underline{v}_2\}$  by promise.

$\therefore \{\underline{v}_1, \underline{v}_2, \underline{v}_3\}$  is lin. ind

**Question 2.** Consider the subspace  $H = \left\{ A \mid A \in \mathcal{M}_{2 \times 2} \text{ and } \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} A = A \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}$ .

a. (1 marks) Is  $\mathbf{0}$  (the  $2 \times 2$  zero matrix) in  $H$ ?

b. (1 marks) Is  $I$  (the  $2 \times 2$  identity matrix) in  $H$ ?

c. (1 mark) For what  $a$  is  $\begin{bmatrix} 2 & 2 \\ 3 & a \end{bmatrix}$  in  $H$ ?

d. (4 marks) Find a basis for  $H$ .

e. (2 marks) Express the matrix you found in part c. relative to the basis found in part d., if possible.

a)  $LHS = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$   
 RHS =  $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

$\therefore \mathbf{0} \in H$   
 b)  $LHS = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

c)  $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 3 & a \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 3 & a \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$   
 $\begin{bmatrix} 2 & 2 \\ -3 & -a \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ a & 3 \end{bmatrix} \Rightarrow a = -3$

$A = a \underbrace{\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}}_{M_1} + c \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & -1 \end{bmatrix}}_{M_2}$

RHS =  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \neq LHS$

$\therefore H = \text{span}\{M_1, M_2\}$

$\therefore I \notin H$

d) Let  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in H$

then  $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$\begin{bmatrix} a & b \\ -c & -d \end{bmatrix} = \begin{bmatrix} b & a \\ d & c \end{bmatrix}$

$\therefore a = b$  and  $A = \begin{bmatrix} a & a \\ c & -c \end{bmatrix}$   
 $d = -c$

$\{M_1, M_2\}$  is lin. ind since  $M_1$  and  $M_2$  are not multiples of each other.  $\therefore \{M_1, M_2\}$  is a basis of  $H$ .

e)  $\left( \begin{bmatrix} 2 & 2 \\ 3 & -3 \end{bmatrix} \right)_\beta = (c_1, c_2) = (2, 3)$

$\begin{bmatrix} 2 & 2 \\ 3 & -3 \end{bmatrix} = 2 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 0 & 0 \\ 1 & -1 \end{bmatrix}$