

Question 1.¹ (1 mark each) Complete each of the following sentences with MUST, MIGHT, or CANNOT.

- A system of linear equations with more equations than variables might have a unique solution.
- If the 3×3 coefficient matrix A has a RREF with a single leading one, then the system $Ax = b$ might be inconsistent when $b = [0 \ 0 \ 1]^T$.
- If the bottom row of a matrix in reduced row-echelon form contains all 0's to the left of the vertical bar and a nonzero entry to the right, then the system must have no solution.
- If A is a square matrix and $A^4 - 2A^2 + A = 0$, then A might be invertible.
- Given an $n \times n$ matrix A . If the system $Ax = b$ is consistent for all $b \in \mathbb{R}^n$, then the system $Ax = 0$ cannot have non-trivial solutions.
- The expression $(B - A)(B + A)$ must be equal to $B^2 - A^2$ if A and B are commutative.
- If E_1, E_2 are elementary matrices, then $E_1 E_2$ might also be an elementary matrix.
- If matrix AB is invertible, then B might be invertible.

Question 2.¹ (5 marks) Given X, A, B , and C are $n \times n$ matrices, solve the following equation for X . Assume any necessary matrices to be invertible.

$$2X^T + A = (XB - C)^T$$

$$2X^T + A = (XB)^T - C^T$$

$$2X^T + A = B^T X^T - C^T$$

$$C^T + A = -2X^T + B^T X^T$$

$$C^T + A = (-2I + B^T)X^T$$

$$(-2I + B^T)^{-1}(C^T + A) = (-2I + B^T)^{-1}(-2I + B^T)X^T$$

$$(-2I + B^T)^{-1}(C^T + A) = X^T$$

$$\begin{aligned} ((-2I + B^T)^{-1}(C^T + A))^T &= (X^T)^T \\ ((C^T + A)^T)((-2I + B^T)^{-1})^T &= X \\ ((C^T + A)^T)((-2I + B^T)^T)^{-1} &= X \\ (C + A)(-2I + B)^{-1} &= X \end{aligned}$$

Question 3.² (5 marks) Find all matrices A , if any, such that $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} A = I_2$

$$\underbrace{\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}}_{B} A = I_2$$

For the product of BA to give a 2×2 matrix, A must be a 3×2 matrix.

Let $A = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}$ then $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a+c+e & b+d+f \\ c+a & d+f \end{bmatrix}$

$$1 = a+c+e$$

$$0 = c+a$$

$$0 = b+d+f$$

$$1 = d+f$$

$$\begin{array}{l} \text{Let } a = t, b = s, c = -t, d = -s, e = t, f = s \\ \text{Then } \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} t & s \\ -t & -s \\ t & s \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \end{array}$$

$$A = \begin{bmatrix} 1 & -1 \\ -t & 1-s \\ t & s \end{bmatrix} \quad t, s \in \mathbb{R}$$

¹From or modified from a John Abbott final examination or WeBWorK

²From a Dawson final examination

Question 4. Given

$$A = \begin{bmatrix} 0 & 0 & -1 & -1 \\ 2 & -2 & 0 & 3 \\ 3 & 0 & 0 & -2 \\ 5 & -2 & -1 & 0 \end{bmatrix} \sim \begin{array}{l} R_1 \leftrightarrow R_2 \\ 2R_1 \rightarrow R_3 \\ 2R_1 \rightarrow R_4 \end{array} \begin{bmatrix} 2 & -2 & 0 & 3 \\ 0 & 0 & -1 & -1 \\ 6 & 0 & 0 & -4 \\ 10 & -4 & -2 & 0 \end{bmatrix} \sim \begin{array}{l} -3R_1 + R_3 \rightarrow R_3 \\ -5R_1 + R_4 \rightarrow R_4 \end{array} \begin{bmatrix} 2 & -2 & 0 & 3 \\ 0 & 0 & -1 & -1 \\ 0 & 6 & 0 & -13 \\ 0 & 6 & -2 & -15 \end{bmatrix}$$

a. (4 marks) Find two row echelon form of the matrix A .

b. (2 marks) Suppose that A is the augmented matrix of a linear system. Write the corresponding system of linear equations. Use one of the REF from part a. to find the solution of the system.

c. (1 mark) Express A as a product of elementary matrices, if possible. Justify.

d. (1 mark) Determine whether A is symmetric, skew-symmetric or neither. Justify.

$$\sim \begin{array}{l} R_2 \leftrightarrow R_3 \\ R_1 \rightarrow R_1 \\ R_2 \rightarrow R_2 \\ R_1 + R_4 \rightarrow R_4 \end{array} \begin{bmatrix} 2 & -2 & 0 & 3 \\ 0 & 6 & 0 & -13 \\ 0 & 0 & 1 & 1 \\ 0 & 6 & -2 & -15 \end{bmatrix} \sim \begin{array}{l} -R_1 \rightarrow R_1 \\ -R_2 + R_4 \rightarrow R_4 \end{array} \begin{bmatrix} 2 & -2 & 0 & 3 \\ 0 & 6 & 0 & -13 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -2 & -2 \end{bmatrix} \sim \begin{array}{l} 2R_3 + R_4 \rightarrow R_4 \end{array} \begin{bmatrix} 2 & -2 & 0 & 3 \\ 0 & 6 & 0 & -13 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

b) From the augmented matrix we have

$$\begin{array}{ll} \textcircled{1} & x_1 - x_2 = \frac{3}{2} \\ \textcircled{2} & x_2 = -\frac{13}{6} \\ \textcircled{3} & x_3 = 1 \end{array}$$

Using back substitution,

$$x_1 = -\frac{13}{6}$$

$$\sim \begin{array}{l} \frac{1}{2}R_1 \rightarrow R_1 \\ \frac{1}{6}R_2 \rightarrow R_2 \end{array} \begin{bmatrix} 1 & -1 & 0 & \frac{3}{2} \\ 0 & 1 & 0 & -\frac{13}{6} \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow \text{a REF of } A$$

$$\sim \begin{array}{l} R_3 + R_2 \rightarrow R_2 \end{array} \begin{bmatrix} 1 & -1 & 0 & \frac{3}{2} \\ 0 & 1 & 1 & -\frac{13}{6} \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow \text{an other REF of } A$$

c) Not expressible as a product of elem. mat. by the equiv. thm.
since the RREF is not I.

sub \textcircled{4} into \textcircled{1}

$$x_1 - \left(-\frac{13}{6}\right) = \frac{3}{2}$$

$$x_1 = \frac{3}{2} - \frac{13}{6} = \frac{-4}{6} = -\frac{2}{3}$$

$$\therefore (x_1, x_2, x_3) = \left(-\frac{2}{3}, \frac{13}{2}, 1\right)$$

d)

$$A^T = \begin{bmatrix} 0 & 2 & 3 & 5 \\ 0 & -2 & 0 & -2 \\ -1 & 0 & 0 & -1 \\ -1 & 3 & -2 & 0 \end{bmatrix} \neq A \therefore \text{not symmetric}$$

$$\begin{bmatrix} 0 & 2 & 3 & 5 \\ 0 & -2 & 0 & -2 \\ -1 & 0 & 0 & -1 \\ -1 & 3 & -2 & 0 \end{bmatrix} \neq -A \therefore \text{not skew-symmetric}$$

Question 5a. (5 marks) Let $A = \begin{bmatrix} 1 & 0 & 5 \\ -1 & 3 & 1 \\ 1 & k & 12 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} -2 \\ 8 \\ h \end{bmatrix}$. Find the value(s) of h and k , if possible, for which the equation $A\mathbf{x} = \mathbf{b}$ has:

a. a unique solution,

b. infinitely many solutions,

c. no solution.

$$\begin{bmatrix} 1 & 0 & 5 & -2 \\ -1 & 3 & 1 & 8 \\ 1 & k & 12 & h \end{bmatrix} \sim R_1 + R_2 \rightarrow R_2 \quad \begin{bmatrix} 1 & 0 & 5 & -2 \\ 0 & 3 & 6 & 6 \\ 0 & k & 7 & h+2 \end{bmatrix} \sim \frac{1}{3}R_2 \rightarrow R_2 \quad \begin{bmatrix} 1 & 0 & 5 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & k & 7 & h+2 \end{bmatrix}$$

a) # var = # leading entries

In order to have 3 leading entries $7-2k \neq 0$
 $7 \neq 2k$
 $\frac{7}{2} \neq k$

$$\sim \begin{bmatrix} 1 & 0 & 5 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 7-2k & h+2-2k \end{bmatrix}$$

b) # var > # leading entries (no leading entry in constant col.)

So $7-2k=0$ and $h+2-2k=0$

$$k = \frac{7}{2}$$

which implies $h = 2k - 2 = 2\left(\frac{7}{2}\right) - 2 = 5$

c) leading entry in the constant col.

So $7-2k=0$ and $h+2-2k \neq 0$. Based on the above
this occurs when $k = \frac{7}{2}$ and $h \neq 5$.

Question 5b. (3 marks) Find the solution set in the case where the above system has infinitely many solutions. Give a particular solution. And the particular solution when the second variable is equal to zero.

To have infinitely many $k = \frac{7}{2}$ and $h = 5$,

$$\begin{bmatrix} 1 & 0 & 5 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Let $x_3 = t$, $t \in \mathbb{R}$

$$\begin{aligned} x_1 &= -2-5t \\ x_2 &= 2-2t \end{aligned}$$

$\therefore (x_1, x_2, x_3) = (-2-5t, 2-2t, t)$, $t \in \mathbb{R}$

and a particular solution when $t=0$, $(x_1, x_2, x_3) = (-2, 2, 0)$

and when $0=x_2$ $\therefore (x_1, x_2, x_3) = (-7, 0, 1)$.

$$\begin{aligned} 0 &= 2-2t \\ t &= 1 \end{aligned}$$

Question 6. (3 marks) A square matrix A is *idempotent* if $A^2 = A$. Prove that if A is idempotent then $(I - 2A) = (I - 2A)^{-1}$.

Premise: $\bullet A$ is idempotent, that is, $A^2 = A$

Conclusion:

$\bullet (I - 2A)$ is invertible and its own inverse.

Need to show that there exist a B st. $(I - 2A)B = I$
 $B(I - 2A) = I$

Let $B = (I - 2A)$

$$\begin{aligned} (I - 2A)B &= (I - 2A)(I - 2A) \\ &= I \cdot I - I(2A) - (2A) \cdot I + (2A)(2A) \\ &= I - 4A + 4A^2 \\ &= I - 4A + 4A = I \end{aligned}$$

$$\therefore (I - 2A)^{-1} = (I - 2A)$$

Question 7. (5 marks) Express $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and its inverse as a product of elementary matrices, if possible. Justify.

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \sim -3R_1 + R_2 \rightarrow R_2 \begin{bmatrix} 1 & 2 \\ 0 & -2 \end{bmatrix} \sim R_2 + R_1 \rightarrow R_1 \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \sim -\frac{1}{2}R_2 \rightarrow R_2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

since the RREF of A is I , A is invertible.³ It also follows that

$$E_3 E_2 E_1 A = I$$

where $I_2 \sim -3R_1 + R_2 \begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} = E_1 \Rightarrow E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$ and $E_3 E_2 E_1 A A^{-1} = I A^{-1}$ by ⁴

$$I_2 \sim R_2 + R_1 \rightarrow R_1 \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = E_2 \Rightarrow E_2^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \quad \text{and} \quad (E_3 E_2 E_1)^{-1} = (A^{-1})^{-1}$$

$$I_2 \sim -\frac{1}{2}R_2 \rightarrow R_2 \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{2} \end{bmatrix} = E_3 \Rightarrow E_3^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \quad E_1^{-1} E_2^{-1} E_3^{-1} = A$$

Question 8.³ (5 marks) Let $Ax = 0$ be a homogeneous system of n linear equations in n unknowns, and let Q be an invertible $n \times n$ matrix. Prove that $Ax = 0$ has only the trivial solution if and only if $(QA)x = 0$ has only the trivial solution.

\Leftrightarrow premise:

$Ax = 0$ has only the trivial sol.

conclusion: Q is invertible

$(QA)x = 0$ has only the trivial sol.

since $Ax = 0$ has only the trivial sol.

A is invertible by the equivalence thm.

QA is then invertible since it's the product of two invertible matrix.

Again by the equiv. thm.

$(QA)x = 0$ has only the trivial sol. since QA is invertible.

\Leftrightarrow

premise: $(QA)x = 0$ has only the triv. sol.

conclusion: Q is invertible

conclusion: $Ax = 0$ has only the trivial sol.

It follows that QA is invertible by the equiv. thm since A . So

$$(QA)^{-1} QA = I$$

$(QA)^{-1}$ is the inverse of A by a thm seen in class. Hence A is invertible and by the equiv. thm $Ax = 0$ has only the trivial sol.

Bonus Question. (5 marks) Prove: $(aA)(bB) = abAB$ where A and B are matrices such that their multiplication is defined and $a, b \in \mathbb{R}$

³From assigned homework.