

Books, watches, notes or cell phones are **not** allowed. The **only** calculators allowed are the Sharp EL-531**. You **must** show all your work, the correct answer is worth 1 mark the remaining marks are given for the work.

Question 1. (3 marks each) Determine whether the following statement is true or false. If the statement is false provide a counterexample. If the statement is true provide a proof of the statement.

a. If A is any skew-symmetric matrix then A^2 is skew-symmetric matrix.

False, Let $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$, A is skew-symmetric since $A^T = -A$

But $A^2 = AA = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$, A^2 is symmetric since $(A^2)^T = A^2$.

Question 2. (5 marks) Let A and B be two 3×3 matrices such that $\det(A) = \begin{vmatrix} a+2b & c & b \\ d+2e & f & e \\ g+2h & i & h \end{vmatrix} = -2$ where $a, d, g \neq 0$, and $\det(B) = 3$. Find the

following: $\det \begin{vmatrix} 2 & 2 & 2 \\ \frac{b}{a} & \frac{e}{d} & \frac{h}{g} \\ \frac{c}{a} & \frac{f}{d} & \frac{i}{g} \end{vmatrix}$.

$$= \det \begin{vmatrix} 2 & 2 & 2 \\ \frac{b}{a} & \frac{e}{d} & \frac{h}{g} \\ \frac{c}{a} & \frac{f}{d} & \frac{i}{g} \end{vmatrix} \xrightarrow{\substack{aC_1 \rightarrow C_1, dC_2 \rightarrow C_2, gC_3 \rightarrow C_3}} \det \begin{vmatrix} 2a & 2d & 2g \\ b & e & h \\ c & f & i \end{vmatrix}$$

$$= 2 \xrightarrow{\frac{1}{2}R_1 \rightarrow R_1} \det \begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix}$$

$$= 2 \det \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} \quad \text{since } \det(A^T) = \det(A)$$

$$= 2(2) = 4$$

$$\xrightarrow{-2C_1 + C_2 \rightarrow C_2} \det \begin{vmatrix} a & c & b \\ d & f & e \\ g & i & h \end{vmatrix} = -2$$

$$\xrightarrow{C_1 \leftrightarrow C_2} \det \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = 2$$

Question 3. (3 marks) Prove that if $A^T A = A$, then A is symmetric and $A = A^2$.

Premise:

$$A^T A = A$$

Conclusion:

A is symmetric

$$A = A^2$$

$$\begin{aligned} A^T &= (A^T A)^T \text{ by premise} \\ &= A^T (A^T)^T \\ &= A^T A \\ &= A \end{aligned}$$

$$\begin{aligned} A^2 &= AA \\ &= A^T A \text{ since } A \text{ is symmetric} \\ &= A. \end{aligned}$$

$\therefore A$ is symmetric

Question 4. (5 marks) If A is an $n \times n$ matrix, the characteristic polynomial $c_A(x)$ of A is defined by $c_A(x) = \det(xI - A)$.

a. (5 marks) Find the eigenvalues λ of $A = \begin{bmatrix} 2 & 2 & -2 \\ 1 & 3 & -1 \\ -1 & 1 & 1 \end{bmatrix}$. That is, find the values of λ for which $c_A(\lambda) = 0$.

b. (3 marks bonus) Find the eigenvector for a non-zero eigenvalue found in part a. That is, find a non-trivial solution $\mathbf{x}$ for each λ where $A\mathbf{x} = \lambda\mathbf{x}$.

$$0 = \det \left(\lambda I - \begin{bmatrix} 2 & 2 & -2 \\ 1 & 3 & -1 \\ -1 & 1 & 1 \end{bmatrix} \right)$$

$$= \begin{vmatrix} \lambda-2 & -2 & 2 \\ -1 & \lambda-3 & 1 \\ 1 & -1 & \lambda-1 \end{vmatrix}$$

$$= \begin{vmatrix} \lambda-2 & 0 & 2 \\ -1 & \lambda-2 & 1 \\ 1 & \lambda-2 & \lambda-1 \end{vmatrix} \quad C_3 + C_2 \rightarrow C_3$$

$$= \begin{vmatrix} \lambda-2 & 0 & 2 \\ -1 & \lambda-2 & 1 \\ 0 & 2\lambda-4 & \lambda \end{vmatrix} \quad R_2 + R_3 \rightarrow R_3$$

$$= (\lambda-2) \begin{vmatrix} \lambda-2 & 1 \\ 2\lambda-4 & \lambda \end{vmatrix} + 2 \begin{vmatrix} -1 & \lambda-2 \\ 0 & 2\lambda-4 \end{vmatrix}$$

$$= (\lambda-2) [(\lambda-2)\lambda - (2\lambda-4)] - 2 [2\lambda-4]$$

$$= (\lambda-2) [\lambda^2 - 2\lambda - 2\lambda + 4] - 4 [\lambda-2]$$

$$= (\lambda-2) [\lambda^2 - 4\lambda]$$

$$= (\lambda-2) \lambda (\lambda-4)$$

$$\lambda=2 \quad \lambda=0 \quad \lambda=4$$

$$b) A\mathbf{x} = \lambda\mathbf{x}$$

$$A\mathbf{x} - \lambda\mathbf{x} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{x} = \mathbf{0}$$

$$\lambda=2: \begin{bmatrix} 0 & 2 & -2 & 0 \\ 1 & 1 & -1 & 0 \\ -1 & 1 & -1 & 0 \end{bmatrix} \sim R_1 \leftrightarrow R_2 \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 2 & -2 & 0 \\ -1 & 1 & -1 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 2 & -2 & 0 \\ 0 & 2 & -2 & 0 \end{bmatrix} \quad R_1 + R_3 \rightarrow R_3$$

$$\sim \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \frac{1}{2}R_2 \rightarrow R_2, -R_2 + R_3 \rightarrow R_3$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad -R_2 + R_1 \rightarrow R_1$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad -R_1 \rightarrow R_1$$

$$\text{Let } \mathbf{z} = t \quad t \in \mathbb{R} \\ x=0 \\ y=t$$

$$\therefore \mathbf{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = t \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

$$\therefore \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \text{ is an eigenvector}$$

$$\text{of } \lambda=2.$$